Soft matter: Density functionals and simulation of simple molecules on graphics cards

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Outline

- **1** GPU Computing
- 2 Physical background
- 3 Tailor expanded functional
- 4 Implementation
- 5 Rosenfeld functional
- 6 Results and outlook

Physical nVidia GPU architecture ...



... and how it looks from a programmers perspective





What we want to do

 Calculate pair correlation functions and density profiles around a test particle in two dimensions.



- Equilibrium: $\rho(\mathbf{r}) = \rho_0 g(\mathbf{r})$.
- Under shear: $\rho(x,y) = \rho_0 g(x,y)$ (which gives us rheological information).

Given the full free energy functional *F*[ρ] of the system the density profile ρ(**r**) is found by minimising

$$\Omega = F[\rho] - \int d\mathbf{r} \
ho(\mathbf{r})(\mu - V(\mathbf{r})).$$

F[ρ] can be expressed by the sum of the ideal gas free energy and the excess free energy

$$F[\rho] = F^{id}[\rho] + F^{ex}[\rho].$$

• For $\rho = \rho_{eq}$ (equilibrium density) Ω is the grand potential.

Density functional for hard discs

Ideal gas and tailor expanded functional:

$$\begin{split} F^{id} &= \int d\mathbf{r} \ \rho(\mathbf{r}) \cdot \ln(\rho_0 - 1) \,, \\ F^{ex} &= \int d\mathbf{r} \ \mu \ \rho(\mathbf{r}) - \frac{1}{2} \int d\mathbf{r} \ d\mathbf{r'} \ c^{(2)}(\mathbf{r} - \mathbf{r'}; \rho_0) \ \Delta \rho(\mathbf{r}) \ \Delta \rho(\mathbf{r'}). \end{split}$$

 $c^{(2)}(\mathbf{r} - \mathbf{r'}; \rho_0)$ is the direct correlation function.

• Differentiation of Ω leads to

$$\rho(\mathbf{r}) = \rho_0 \cdot \exp\left[-V(\mathbf{r}) + c^{(2)} * \Delta\rho\right].$$

Identifying the main computational steps

- Solution by iterating $\rho_{i+1}(\mathbf{r}) = \rho_0 e^{-V(\mathbf{r}) + c^{(2)} * \Delta \rho_i}$.
- Calculation will take place on a 2D lattice of size $n \times n$.
- V(r) constant potential, infinite in the area occupied by our test particle and 0 everywhere else.
- $c^{(2)}$ constant and the fourier transformed values can be stored in the graphic cards memory.
- $\Delta \rho = \rho(\mathbf{r}) \rho_0$ has to be calculated each step.
- The convolution c⁽²⁾ * Δρ will be calculated in fourier space, making fourier transformations necessary. Δρ has to be calculated in each step. The fourier transformations will be the most time consuming part of the calculation.

The Fast Fourier Transformation (FFT)

- The direct evaluation of the fourier transformation $X_k = \sum_{n=0}^{N-1} x_n e^{-i2\pi k \frac{n}{N}}$ runs in O(N²).
- Cooley-Tukey FFT algorithm divides one fourier transformation of size N into two of size N/2

$$X_{k} = \sum_{m=0}^{\frac{N}{2}-1} x_{2m} e^{-i2\pi k \frac{2m}{N}} + \sum_{m=0}^{\frac{N}{2}-1} x_{2m+1} e^{-i2\pi k \frac{2m+1}{N}}$$
$$= \sum_{m=0}^{M-1} x_{2m} e^{-i2\pi k \frac{m}{M}} + e^{-\frac{i2\pi}{N}k} \sum_{m=0}^{M-1} x_{2m+1} e^{-i2\pi k \frac{m}{M}}$$
$$= \begin{cases} E_{k} + e^{-\frac{i2\pi}{N}k} O_{k} & k < M, \\ E_{k-M} - e^{-\frac{i2\pi}{N}(k-M)} O_{k-M} & k \ge M. \end{cases}$$
using $E_{k+M} = E_{k}, O_{k+M} = O_{k}$ even and odd FT.

• Recursive application leads to runtime of $O(N \log N)$

- CPU: Intel Core2 Quad CPU Q6700 @ 2.66GHz
- GPU: NVidia GeForce GTX 280
- NVidia Driver Version: 185.18.14
- X Server Version: 1.5.2 (11)
- Operating System: SUSE Linux 11.1, 64 bit
- Kernel Version: 2.6.27.29

Implementation (1)

The CUFFT library is used for the fourier transformations.

```
#include <cufft.h>
```

```
_-device_- Complex* d_drho;
_-device_- Complex* d_fold;
_-device_- cufftHandle plan;
cufftPlan2d(&plan, size_x, size_y, CUFFT_C2C);
cufftExecC2C(plan, (cufftComplex *)d_drho, (cufftComplex *)d_drho, CUFFT_FORWARD);
cufftExecC2C(plan, (cufftComplex *)d_fold, (cufftComplex *)d_fold, CUFFT_INVERSE);
cufftDestroy(plan);
cudaFree(d_fold);
cudaFree(d_drho);
```

- CUFFT is inspired by the popular FFTW C library.
- CUBLAS (inspired by the popular BLAS C library) is also available but not shown here.

Implementation (2)

#include <cufft.h>

 Evaluating the exponential function requires point-wise matrix manipulation and can easily be parallelized.

```
__global__ void function(cufftComplex* res, cufftComplex* v, cufftComplex* fold,
     float r. int sx. int sv) {
    int X = blockIdx.x * blockDim.x + threadIdx.x;
    int Y = blockIdx.y * blockDim.y + threadIdx.y;
    int pos = X+Y*sx:
    if (X < sx \&\& Y < sy) {
        res[pos].x = r * exp(-v[pos].x + fold[pos].x);
        res[pos], v = 0;
    }
}
void iterate_gpu() {
    dim3 dimBlock(BLOCK_SIZE, BLOCK_SIZE);
    int GRID_X = (int) ceil((float) size_x/(float) BLOCK_SIZE);
    int GRID_Y = (int) ceil((float) size_y/(float) BLOCK_SIZE);
    dim3 dimGrid(GRID_X, GRID_Y);
    [...]
    function <<<<dimGrid, dimBlock >>>(d_fold, d_v, d_fold, rho0, size_x, size_y);
    [...]
}
```

Implementation (3)

For convergence we need the difference between two iterations.

```
__global__ void compare_fast(cufftComplex* a, cufftComplex* b, int sx, int sy,
     float dx. float r)
{
    int X = blockIdx.x * blockDim.x + threadIdx.x;
    int Y = blockIdx.y * blockDim.y + threadIdx.y;
    int pos = X+Y*sx:
    if (pos < MAX_BLOCK)
        __shared__ float c[MAX_BLOCK];
        c[pos] = a[pos + (int) (r/dx)] \cdot x - b[pos + (int) (r/dx)] \cdot x;
        c[pos] = c[pos];
        c[pos] /= (float) MAX_BLOCK;
        __syncthreads();
        for (int s=MAX_BLOCK/2; s>0; s/=2)
        ł
            if (pos < s)
                c[pos] += c[pos + s];
            __syncthreads();
        if (pos == 0)
                 a[0].x = c[0];
                 a[0], v = 0:
    }
}
```

Radial distribution function g(r)



Figure: Comparison between DFT (red) and MC simulation (green) at a density of $\rho_0 = 0.65$. More accurate DFT results can be optained by using a better functional instead of the simple tailor expansion used in this example.

• New functional with weighted densities (Rosenfeld functional):

$$F^{\text{ex}} = \int d^2 r \left[-\mu_0 \cdot \ln(1 - n_2) + \frac{1}{4\pi} \frac{n_1^2 - \mathbf{n}^2}{1 - n_2} \right]$$

with $n_i(\mathbf{x}) = \int \rho(\mathbf{x}') \cdot \omega_i(\mathbf{x} - \mathbf{x}') d\mathbf{x}'$
and $\omega_1 = \delta(R - r), \ \omega_2 = \Theta(R - r), \ \omega = -\nabla\omega_2.$

• New equation to iterate:

$$\rho = \rho_0 \cdot \exp\left[-\frac{\delta F}{\delta \rho} + \mu^{ex} - V^{ex}\right]$$

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- The ω_i are constant and need to be calculated once.
- The n_i have to be calculated in every time step which leads to an increase in the number of fourier transformations performed in each step.
- All these fields have to be available in the graphic cards memory, leading to a lot higher overall memory consumption.
- Maximum theoretical lattice size on currently available cards is 4096x4096 for 4GB cards, 2048x2048 has been achieved with our hardware, most runs are performed on a 1024x1024 grid.

Benchmarking

A typical run on a 1024 × 1024 lattice:

#Initialization time: 208.862 ms #FFT time: 2272.37 ms #Function evaluation time: 277.565 ms #Ioops: 377 #Overall time: 4101.56 ms

- Overall time is larger then the sum of the individual parts due to a "GPU boot" which has to occur before initialization.
- The ratio of fourier transformation to other calculations is about 8 : 1 which is similar to CPU calculations.
- The computation is a factor of 100 faster then a naive CPU implementation (using FFTW).
- The use of double precision has no significant impact on the result.

- Calculations in 2D allow for the addition of shear and similar effects.
- Three body correlation functions can be efficiently calculated on the GPUs.
- Realistic results are expected using the Rosenfeld functional.
- 3D systems can be solved, memory constraints however will only allow for small grid sizes: Up to is possible 128³ with the currently available cards while 512³ is necessary to be able to compete with CPU calculations.